

Product datasheet

Specifications



Variable speed drive, Altivar Process ATV600, ATV650, 30 kW, 400...480 V, IP55

ATV650D30N4

Main

Range of product	Altivar Process ATV600
Product or component type	Variable speed drive
Product specific application	Process and utilities
Device short name	ATV650
Variant	Standard version
Product destination	Asynchronous motors Synchronous motors
EMC filter	Integrated with 50 m conforming to EN/IEC 61800-3 category C2 Integrated with 150 m conforming to EN/IEC 61800-3 category C3
IP degree of protection	IP55 conforming to IEC 60529 IP55 conforming to IEC 61800-5-1
[Us] rated supply voltage	380...480 V
Type of cooling	Forced convection
Supply frequency	50...60 Hz - 5...5 % 380...480 V - 15...10 %
Motor power kW	22.0 kW (heavy duty) 30.0 kW (normal duty)
Motor power hp	25 hp heavy duty 40 hp normal duty
Line current	34.4 A at 480 V (normal duty) 34.1 A at 380 V (heavy duty) 29.9 A at 480 V (heavy duty) 53.3 A at 380 V (normal duty)
Prospective line Isc	50 kA
Apparent power	24.9 kVA at 480 V (heavy duty) 38.2 kVA at 480 V (normal duty)
Continuous output current	39.2 A at 4 kHz for heavy duty 46.3 A at 4 kHz for heavy duty
Asynchronous motor control profile	Variable torque standard Optimized torque mode Variable torque standard
Synchronous motor control profile	Synchronous reluctance motor Permanent magnet motor
Speed drive output frequency	0.1...500 Hz
Nominal switching frequency	4 kHz
Switching frequency	4...12 kHz with derating factor 2...12 kHz adjustable

Safety function	STO (safe torque off) SIL 3
Discrete input logic	16 preset speeds
Communication port protocol	Modbus serial Modbus TCP Modbus TCP
Option card	Slot A: communication module, PROFINET Slot A: communication module, DeviceNet Slot A: communication module, Modbus TCP/EtherNet/IP Slot A: communication module, CANopen daisy chain RJ45 Slot A: communication module, CANopen SUB-D 9 Slot A: communication module, CANopen screw terminals Slot A/slot B: digital and analog I/O extension module Slot A/slot B: output relay extension module Slot A: communication module, Ethernet IP/Modbus TCP/MD-Link Communication module, BACnet MS/TP Communication module, Ethernet Powerlink Slot A: communication module, Profibus DP V1

Complementary

Mounting mode	Wall mount
Maximum transient current	58.8 A during 60 s (heavy duty) 67.7 A during 60 s (heavy duty)
Network number of phases	3 phases
Discrete output number	0
Discrete output type	Relay outputs R1A, R1B, R1C 250 V AC 3000 mA Relay outputs R1A, R1B, R1C 30 V DC 3000 mA Relay outputs R2A, R2C 250 V AC 5000 mA Relay outputs R2A, R2C 30 V DC 5000 mA Relay outputs R3A, R3C 250 V AC 5000 mA Relay outputs R3A, R3C 30 V DC 5000 mA
Output voltage	<= power supply voltage
Permissible temporary current boost	1.5 x In during 60 s (heavy duty) 1.1 x In during 60 s (normal duty)
Motor slip compensation	Automatic whatever the load Not available in permanent magnet motor law Adjustable Adjustable
Acceleration and deceleration ramps	Linear adjustable separately from 0.01...9999 s
Physical interface	Ethernet 2-wire RS 485
Braking to standstill	By DC injection
Protection type	Safe torque off: motor Motor phase break: motor Thermal protection: drive Safe torque off: drive Overheating: drive Overcurrent between output phases and earth: drive Overload of output voltage: drive Short-circuit protection: drive Motor phase break: drive Overvoltages on the DC bus: drive Line supply overvoltage: drive Line supply undervoltage: drive Line supply phase loss: drive Overspeed: drive Break on the control circuit: drive Thermal protection: motor
Transmission rate	10, 100 Mbits 4800 bps, 9600 bps, 19200 bps, 38.4 Kbps
Frequency resolution	Analog input: 0.012/50 Hz Display unit: 0.1 Hz
Transmission frame	RTU
Electrical connection	Motor: screw terminal 16 mm ² /AWG 6 Line side: screw terminal 10...16 mm ² /AWG 8...AWG 6 Control: removable screw terminals 0.5...1.5 mm ² /AWG 20...AWG 16
Connector type	RJ45 (on the remote graphic terminal) for Modbus serial RJ45 (on the remote graphic terminal) for Ethernet/Modbus TCP

Data format	8 bits, configurable odd, even or no parity
Type of polarization	No impedance
Exchange mode	Half duplex, full duplex, autonegotiation Ethernet/Modbus TCP
Number of addresses	1...247 for Modbus serial
Method of access	Slave Modbus TCP
Supply	<p>Internal supply for reference potentiometer (1 to 10 kOhm): 10.5 V DC +/- 5 %, <10 mA, protection type: overload and short-circuit protection</p> <p>Internal supply for digital inputs and STO: 24 V DC (21...27 V), <200 mA, protection type: overload and short-circuit protection</p> <p>External supply for digital inputs: 24 V DC (19...30 V), <1.25 mA, protection type: overload and short-circuit protection</p>
Local signalling	<p>3 LEDs (dual colour) for embedded communication status</p> <p>4 LEDs (dual colour) for communication module status</p> <p>1 LED (red) for presence of voltage</p> <p>3 LEDs for local diagnostic</p>
Width	290 mm
Height	910 mm
Depth	340 mm
Product weight	50 kg
Analogue input number	3
Analogue input type	<p>AI1, AI2, AI3 software-configurable voltage: 0...10 V DC, impedance: 31.5 kOhm, resolution 12 bits</p> <p>AI1, AI2, AI3 software-configurable current: 0...20 mA, impedance: 250 Ohm, resolution 12 bits</p> <p>AI2 voltage analog input: - 10...10 V DC, impedance: 31.5 kOhm, resolution 12 bits</p>
Discrete input number	8
Discrete input type	DI7, DI8 programmable as pulse input: 0...30 kHz, 24 V DC (<= 30 V)
Input compatibility	<p>DI5, DI6: discrete input level 1 PLC conforming to IEC 65A-68</p> <p>STOA, STOB: discrete input level 1 PLC conforming to EN/IEC 61131-2</p> <p>DI1...DI6: discrete input level 1 PLC conforming to EN/IEC 61131-2</p> <p>Positive logic (source) (DI1...DI8), < 5 V (state 0), > 11 V (state 1)</p> <p>Negative logic (sink) (DI1...DI8), > 16 V (state 0), < 10 V (state 1)</p>
Analogue output number	2
Analogue output type	<p>Software-configurable voltage AQ1, AQ2: 0...10 V DC impedance 470 Ohm, resolution 10 bits</p> <p>Software-configurable current AQ1, AQ2: 0...20 mA, resolution 10 bits</p> <p>Software-configurable current DQ-, DQ+: 30 V DC</p> <p>Software-configurable current DQ-, DQ+: 100 mA</p>
Sampling duration	<p>5 ms +/- 1 ms (DI5, DI6) - discrete input</p> <p>5 ms +/- 0.1 ms (AI1, AI2, AI3) - analog input</p> <p>10 ms +/- 1 ms (AO1) - analog output</p> <p>2 ms +/- 0.5 ms (DI1...DI4) - discrete input</p>
Accuracy	<p>+/- 1 % AO1, AO2 for a temperature variation 60 °C analog output</p> <p>+/- 0.6 % AI1, AI2, AI3 for a temperature variation 60 °C analog input</p>
Linearity error	<p>AO1, AO2: +/- 0.2 % for analog output</p> <p>AI1, AI2, AI3: +/- 0.15 % of maximum value for analog input</p>
Relay output number	3
Relay output type	<p>Configurable relay logic R2: sequence relay NO electrical durability 100000 cycles</p> <p>Configurable relay logic R3: sequence relay NO electrical durability 100000 cycles</p> <p>Configurable relay logic R1: fault relay NO/NC electrical durability 100000 cycles</p>
Refresh time	Relay output (R1, R2, R3): 5 ms (+/- 0.5 ms)
Minimum switching current	Relay output R1, R2, R3: 5 mA at 24 V DC
Maximum switching current	<p>Relay output R1, R2, R3 on resistive load, cos phi = 1: 3 A at 30 V DC</p> <p>Relay output R1, R2, R3 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 250 V AC</p> <p>Relay output R1, R2, R3 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 30 V DC</p> <p>Relay output R1, R2, R3 on resistive load, cos phi = 1: 3 A at 250 V AC</p>
Isolation	Between power and control terminals
Maximum output frequency	500 kHz
Maximum input current	53.3 A
Variable speed drive application selection	Building - HVAC compressor centrifugal

Motor power range AC-3	30...50 kW at 380...440 V 3 phases
Quantity per set	1
Enclosure mounting	Wall mounted
Environment	
Insulation resistance	> 1 MOhm 500 V DC for 1 minute to earth
Noise level	69.7 dB conforming to 86/188/EEC
Operating position	Vertical +/- 10 degree
Maximum THDI	<48 % from 80...100 % of load conforming to IEC 61000-3-12
Electromagnetic compatibility	Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 1.2/50 µs - 8/20 µs surge immunity test level 3 conforming to IEC 61000-4-5 Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6 Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2
Pollution degree	2 conforming to EN/IEC 61800-5-1
Vibration resistance	1 gn (f= 13...200 Hz) conforming to IEC 60068-2-6 1.5 mm peak to peak (f= 2...13 Hz) conforming to IEC 60068-2-6
Shock resistance	15 gn for 11 ms conforming to IEC 60068-2-27
Relative humidity	5...95 % without condensation conforming to IEC 60068-2-3
Ambient air temperature for operation	40...50 °C (with derating factor) -15...40 °C (without derating)
Ambient air temperature for storage	-40...70 °C
Operating altitude	1000...4800 m with current derating 1 % per 100 m <= 1000 m without derating
Product certifications	CSA TÜV UL Bureau Veritas DNV-GL ABS CSA
Marking	CE
Standards	EN/IEC 61800-3 EN/IEC 61800-3 environment 1 category C2 EN/IEC 61800-3 environment 2 category C3 EN/IEC 61800-5-1 IEC 61000-3-12 IEC 60721-3 IEC 61508 IEC 13849-1 UL 508C
Overvoltage category	III
Regulation loop	Adjustable PID regulator
	69.7 dB
	3

Packing Units

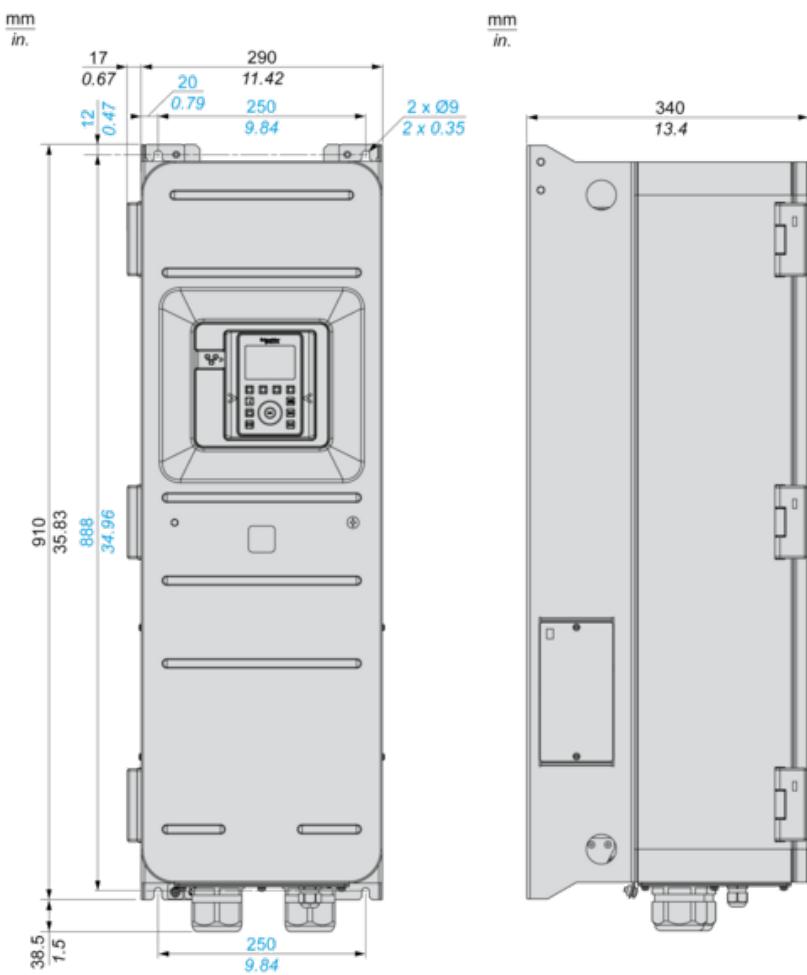
Unit Type of Package 1	PCE
Number of Units in Package 1	1
Package 1 Height	64.0 cm
Package 1 Width	43.0 cm
Package 1 Length	112.0 cm
Package 1 Weight	54.0 kg

Offer Sustainability

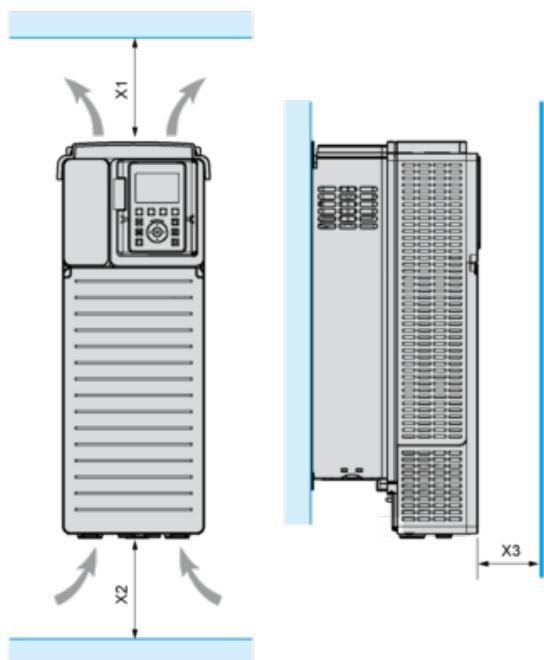
Sustainable offer status	Green Premium product
REACH Regulation	REACH Declaration
EU RoHS Directive	Pro-active compliance (Product out of EU RoHS legal scope) EU RoHS Declaration
Mercury free	Yes
China RoHS Regulation	China RoHS declaration
RoHS exemption information	Yes
Environmental Disclosure	Product Environmental Profile
Circularity Profile	End of Life Information
WEEE	The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins
Upgradeability	Upgraded components available

Dimensions

Front and Left Views



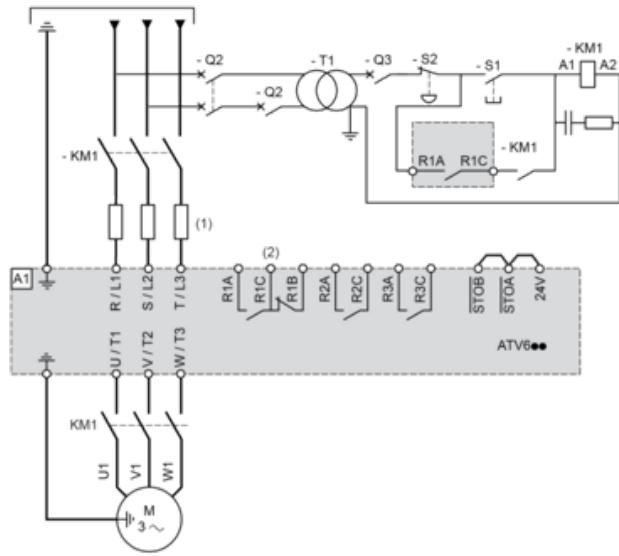
Clearances



X1	X2	X3
≥ 100 mm (3.94 in.)	≥ 100 mm (3.94 in.)	≥ 10 mm (0.39 in.)

Three-Phase Power Supply with Upstream Breaking via Line Contactor

Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1



(1) Line choke if used

(2) Use relay R1 set to operating state Fault to switch Off the product once an error is detected.

A1 : Drive

KM1 : Line Contactor

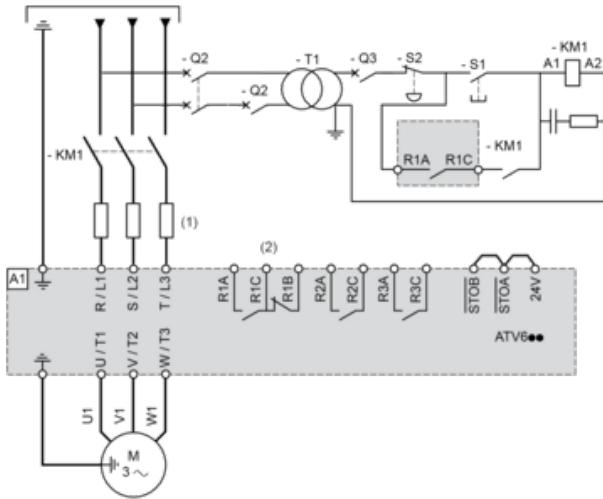
Q2, Q3 : Circuit breakers

S1, S2 : Pushbuttons

T1 : Transformer for control part

Three-Phase Power Supply with Downstream Breaking via Contactor

Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1

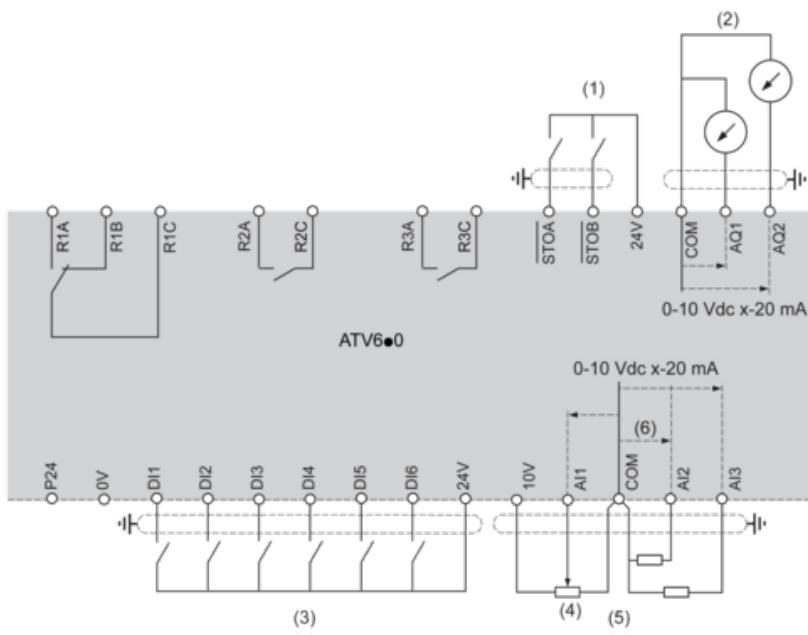


(1) Line choke if used

(2) Use relay R1 set to operating state Fault to switch Off the product once an error is detected.

A1 : Drive

KM1 : Contactor

Control Block Wiring Diagram

(1) Safe Torque Off

(2) Analog Output

(3) Digital Input

(4) Reference potentiometer

(5) Analog Input

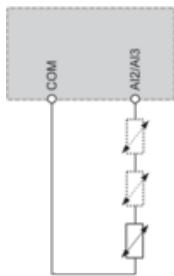
R1A, R1B, R1C : Fault relay

R2A, R2C : Sequence relay

R3A, R3C : Sequence relay

Sensor Connection

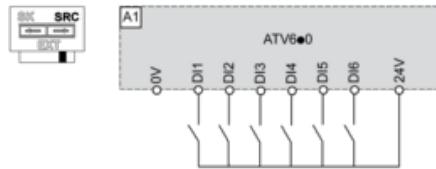
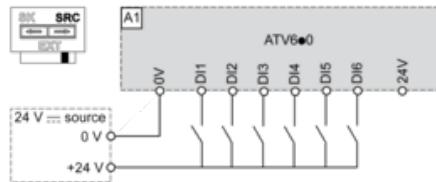
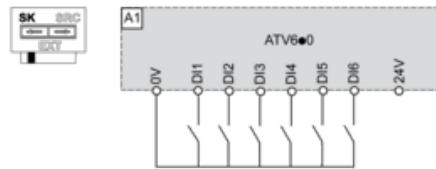
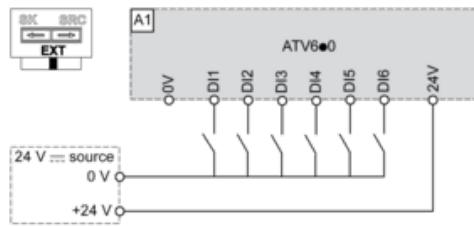
It is possible to connect either 1 or 3 sensors on terminals AI2 or AI3.



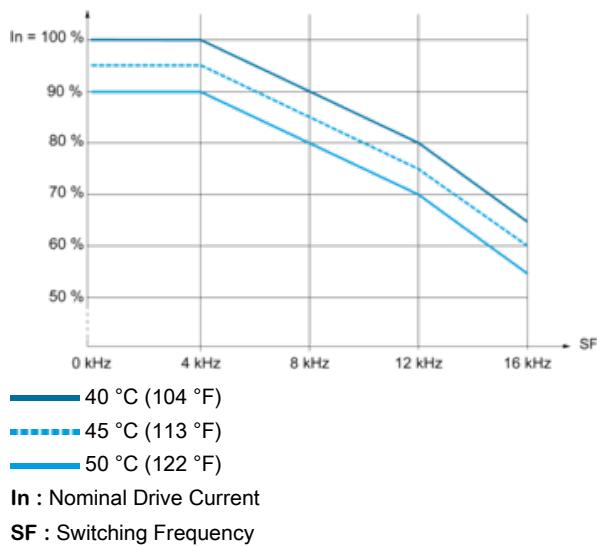
Sink / Source Switch Configuration

The switch is used to adapt the operation of the logic inputs to the technology of the programmable controller outputs.

- Set the switch to Source (factory setting) if using PLC outputs with PNP transistors.
- Set the switch to Ext if using PLC outputs with NPN transistors.

Switch Set to SRC (Source) Position Using the Output Power Supply for the Digital Inputs**Switch Set to SRC (Source) Position and Use of an External Power Supply for the DIs****Switch Set to SK (Sink) Position Using the Output Power Supply for the Digital Inputs****Switch Set to EXT Position Using an External Power Supply for the DIs**

Derating Curves



Recommended replacement(s)